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5. [Hexapod using 60mm \(1/5 **scale**\) Servos - Trossen **Robotics** Community](#)

Modular **Robotics** Systems · Advanced **Robotics** and **Tools** I've never built or played with the quarter-**scale** or 1/5-**scale** servos. ...

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Using boxes, spheres, cylinders and other basic primitives create a simple **robot**. Use all 4 views and the transform, rotate, and **scale tools** ...

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7. [Scaling intelligent behaviour in the ARBIB autonomous robot - ECS ...](#)

Apr 13, 2008 ... **Scaling** intelligent behaviour in the ARBIB autonomous **robot**.

Damper, R. I. and French, R. L. B. (2001) ... **Tools**. Look up in Google Scholar ...

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by RI Damper - 2001 - [All 4 versions](#)

8. [Human-robot interaction - Wikipedia, the free encyclopedia](#)

Apr 23, 2009 ... Human-robot interaction (HRI) is the study of interactions between people ... **Tool** - toy **scale**. Is the system designed to solve a problem ...

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9. [TUT - Course Catalog 2008-2009 - TTE-5106 Design of Robot Systems](#)

To learn to design effective **robot** workcells to perform specified task based on ...

Other **scaled**, Hours. New **tools** and study methods, 6. Total sum, 165.5 ...

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2.3 Tradeoff Problem of havior? **tools** or developer to make **robot** motion or behav-.

"Share" and "Extension". When constructing a large **scale** software, "Share" ...

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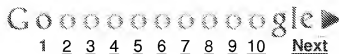
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